

Rotary Measuring Technology

Absolute singleturn encoder hollow shaft version

Stainless steel Type 5876



Your benefit

- Integrativ Technology®
Patented new type of construction integrates all components; use of an opto-asic and 6-layer multilayer technology now on just a single PCB
- resolution up to 14 bits.
- Improved EMV-charecteristics and highest shock resistance on the market (>2500 m/s², 6 ms acc. to DIN IEC 68-2-27).
- SSI or parallel interface

- Various options (z.B. LATCH, SET....)
 - Temperature and ageing compensation
 - Short-circuit proof outputs
- Produkt features**
- resolution up to 14 bits, singleturn
 - ø 58 mm
 - Housing ø 12 mm
 - IP 66
 - Gray, Binary or BCD code
 - available as explosion proof zone 2 and 22

Mechanical characteristics:

Speed with sealing ¹⁾ :	max. 6000 min ⁻¹
Rotor moment of inertia:	appr. 6 x 10 ⁻⁶ kgm ²
Starting torque:	< 0,05 Nm
Weight:	appr. 0,6 kg
Protection acc. to EN 60 529 with sealing:	IP 66
Working temperature with sealing:	-20° C ... +80 °C ²⁾³⁾
Operating temperature with sealing:	-20° C ... +85 °C ²⁾⁴⁾
Shaft/body:	stainless steel
Shock resistance acc. to DIN-IEC 68-2-27:	2500 m/s ² , 6 ms
Vibration resistance acc. to DIN-IEC 68-2-6:	100 m/s ² , 10...2000 Hz

¹⁾for continuous operation max. 1500 min⁻¹

²⁾non-condensing

³⁾70 °C with cable

⁴⁾80 °C with cable

Divisions and code types available at short notice

Gray/Binary

250, 360¹⁾, 500, 720¹⁾, 900, 1000¹⁾, 1024 (10 Bit)¹⁾, 1250, 1440, 1800, 2000, 2500, 2880, 3600¹⁾, 4000, 4096 (12 Bit)¹⁾, 5000, 7200, 8192 (13 Bit)¹⁾, 16384 (14 Bit)¹⁾

BCD

250, 360¹⁾, 500, 720¹⁾, 900, 1000¹⁾, 1024 (10 Bit)¹⁾, 1250, 1440, 1800, 2000

Other on request

¹⁾Preferred divisions are bold

Electrical characteristics:

Interface type:	Synchronous-Serial (SSI)	Synchronous-Serial (SSI)	Parallel	Parallel
Supply voltage (U _B):	5 V DC (± 5 %)	10 ... 30 V DC	5 V DC (± 5 %)	10 ... 30 V DC
Output driver:	RS 485	RS 485	Push-pull	Push-pull
Current consumption typ.:	89 mA	89 mA	109 mA	109 mA
(no load) max.:	138 mA	138 mA	169 mA	169 mA
Permissible load/channel:	max. +/- 20 mA	max. +/- 20 mA	max. +/- 10 mA	max. +/- 10 mA
Word change frequency:	max. 15.000/s	max. 15.000/s	40.000/s	40.000/s
SSI pulse rate min./max.:	100 kHz/500 kHz	100 kHz/500 kHz	-	-
Signal level high:	typ. 3,8 V	typ. 3,8 V	min. 3,4 V	min. U _B - 2,8 V
Signal level low (I _{Load} = 20 mA):	typ. 1,3 V	typ. 1,3 V	-	-
(I _{Load} = 10 mA):	-	-	max. 1,5 V	max. 1,8 V
(I _{Load} = 1 mA):	-	-	max. 0,3 V	-
Rise time tr (without cable):	max. 100 ns	max. 100 ns	max. 0,2 µs	max. 1 µs
Fall time tf (without cable):	max. 100 ns	max. 100 ns	max. 0,2 µs	max. 1 µs
Short circuit proof outputs ¹⁾ :	yes	yes ²⁾	yes	yes
Reverse connection protection at U _B :	no	yes	no	yes
Conforms to CE requirements acc. to EN 61000-6-1, EN 61000-6-4 and EN 61000-6-3				

¹⁾When supply voltage correctly applied U_B

²⁾ Only one channel at a time: When U_B = 5 V DC, short-circuit to channel, 0 V or U_B is permitted.
When U_B = 10 ... 30 V DC short-circuit to channel or 0 V is permitted.

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Control Inputs:

Up/down input to switch the counting direction

As a standard, absolute encoders deliver increasing code values when the shaft rotates clockwise (cw), when looking from the shaft side. When the shaft rotates counter-clockwise (ccw), the output delivers accordingly decreasing code values.

As long as the Up/down input receives the corresponding signal (high), this feature is reversed. Clockwise rotation will deliver decreasing code values while counter-clockwise rotation will deliver increasing code values.

The response time is:

for 5 V DC supply voltage, 0.4 ms
for 10 ... 30 V DC supply voltage, 2 ms.

SET input

This input is used to reset (to zero) the encoder. A control pulse (high) sent to this input allows storing the current position value as new zero position in the encoder.

Switching level of the control inputs

Supply voltage:	5 V DC	10 ... 30 V DC
low	≤1,7 V	≤ 4,5 V
high	≥3,4 V	≥8,7 V

Note :

before activating the SET input after supplying the encoder with the supply voltage, a counting direction (cw or ccw) must be defined univocally on the Up/down input!

The response time is : for 5 V DC supply voltage, 0.4 ms
for 10 ... 30 V DC supply voltage, 2 ms.

LATCH input

This input is used to „freeze“ the current position value. The position value will be statically available on the parallel output as long as this input will remain active (high).

The response time is : for 5 V DC supply voltage, 140 µs,
for 10 ... 30 V DC supply voltage, 200 µs.

Terminal assignment (SSI interface with 12pin plug):

Sig.:	0V	+U _B	+T	-T	+D	-D	SET	V/R	
Pin:	1	2	3	4	5	6	7	8	
Col.:	WH	BN	GN	YE	GY	PK	BU	RD	

T: Clock signal

D: Data signal

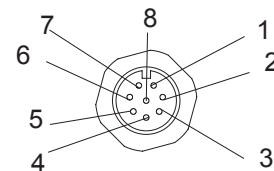
ST: SET input. The current position value is stored as new zero position.

VR: Up/down input. As long as this input is active, decreasing code values are transmitted when shaft turning clockwise.

Insulate unused outputs before initial start-up.

Top view of mating side, male contact base:

8-pin plug



Terminal assignment (Parallel interface, 14 bits and max. 2 options, cable version):

Sig.:	0V	+U _B	1	2	3	4	5	6	7	8	9	10	11	12	13	SET V/R	V/R Latch	14	⏏
Col.:	WH	BN	GN	YE	GY	PK	BU	RD	BK	VT	GY PK	RD BU	WH GN	BN GN	WH YE	YE BN	WH GY	GY BN	

M12 x 1, 8-pin



Your benefit

- Pre-assembled M12 x 1 coupling
- Saves time and money
- Various lengths up to 15 m can be delivered, lengths over 15 m on request
- For simple mounting in the field

Product features

- Polyether-polyurethane cable
- Resistant to oil and sea-water
- IP 67
- 8-pin
- Single-ended

see page 214

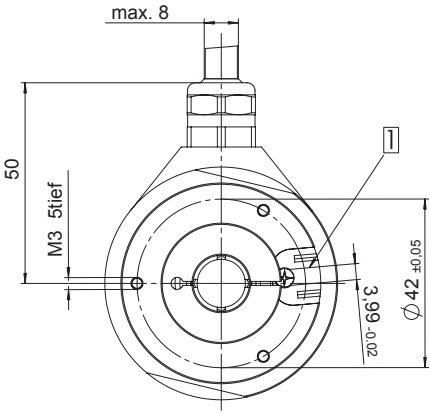
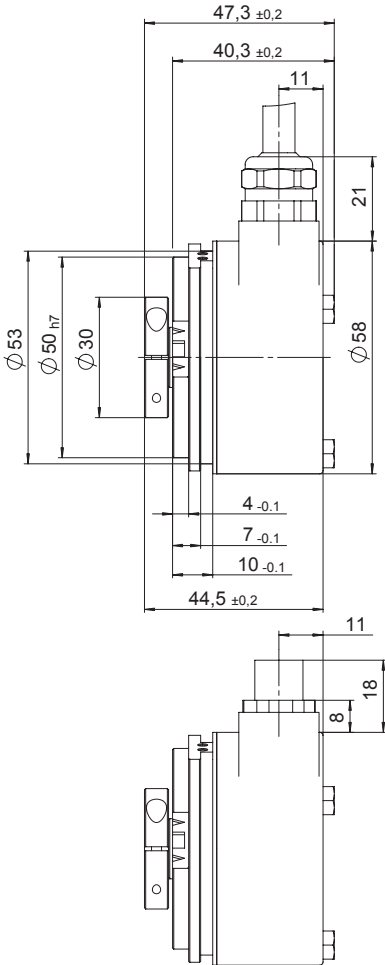
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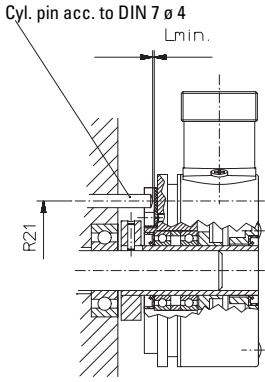
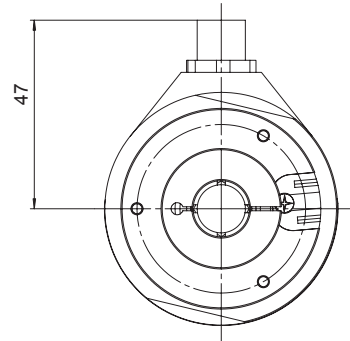
Dimensions:

Flange type 1



□ torque stop slot
 Recommendation:
 Cyl.-pin according to DIN 7 ø 4

Flange type 3



Mounting advice:

1) To mount a hollow shaft encoder, we recommend to use a torque stop pin that fits into the torque stop slot or a stator coupling.

2) When mounting the encoder ensure that Lmin. is larger than the axial play of the drive. Danger of mechanical running out.

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Order code:

8.5876.XXXX.XXXX

Flange	
1 =	Flange type 1 with through shaft
2 =	Flange type 1 with blind hole shaft
3 =	Flange type 3 with stator coupling
4 =	Flange type 2 with blind hole shaft

Hollow shaft	
6 =	∅ 10 mm
8 =	∅ 12 mm

Interface and supply voltage	
1 =	SSI with 5 V supply voltage
2 =	SSI with 10 ... 30 V supply voltage
3 =	Parallel with 5 V supply voltage
4 =	Parallel with 10 ... 30 V supply voltage

Options	
2 =	SET ¹⁾ and V/R
3 ²⁾ =	SET and Latch ¹⁾
4 ²⁾ =	V/R ¹⁾ and Latch
Alarm output on request	
1 ¹⁾	with 14 bits parallel output and 17pin plug
2 ²⁾	not with SSI interface

Code type and division	
use corresponding table	

Type of connection	
1 ^{a)} =	radial cable 1 m PVC-cable)
2 ^{b)} =	radial plug without mating connector

a) in connection with parallel- oder SSI- output
b) in connection with SSI-output

Preferred types are fat marked

Accessories:

Corresponding mating connector to connection type 2

- at SSI interface

8 pin plug 05.CMB8181-0

Mounting set:

Ord.-No. 8.0010.4600.0000 see page 237

Stator coupling two wings

for high dynamic application

Order-No.: 8.0010.4D00.0000 see page 235

Tether arm short

Order-No.: 8.0010.4R00.0000 see page 238

Code type and division with parallel output

Interface and supply voltage, version 3 or 4 (Parallel)

Division	Order code Gray/Gray-Excess	Order code Binary	Order code BCD
250	E02	B02	D02
360¹⁾	E03	B03	D03
500	E05	B05	D05
720¹⁾	E07	B07	D07
900	E09	B09	D09
1000¹⁾	E01	B01	D01
1024 (10 Bit)	G10	B10	D10
1250	E12	BA2	DA2
1440	E14	BA1	DA1
1800	E18	B18	D18
2000	E20	B20	D20
2500	E25	B25	
2880	E28	B28	
3600 ¹⁾	E36	B36	
4000	E40	B40	
4096 (12 Bit)	G12	B12	
5000	E50	B50	
7200	E72	B72	
8192 (13 Bit)	G13	B13	
16384 (14 Bit)	G14	B14	

Preferred divisions are bold

Code type and division for encoder with SSI-Output

Interface and supply voltage, version 1 or 2 (SSI):

Division	Order code Gray	Order code Binary
1024 (10 Bit)	G10	B10
4096 (12 Bit)	G12	B12
8192 (13 Bit)	G13	B13
16384 (14 Bit)	G14	B14